

1 RS-485 (Modbus/Mimic)

The factory default configuration is for the RS-485 as a Modbus Slave.

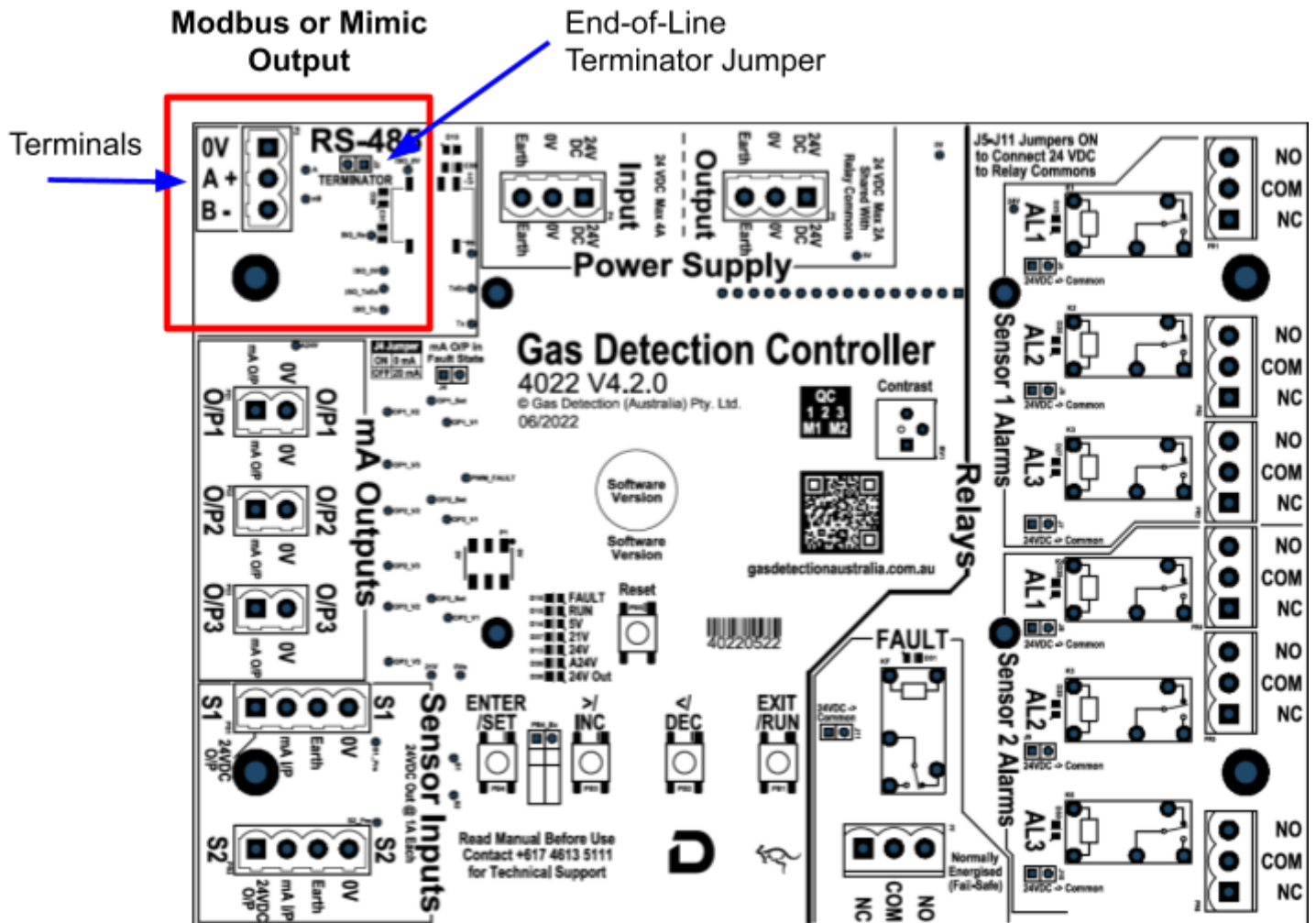


Figure 1: 4022 PCB outline showing RS-485 connection

1.1 Modbus Protocol

The 4022 implements an isolated RS-485 (TIA/EIA-485) MODBUS (V1.1b3) compliant **RTU** slave using 9600 baud (**bps**), 8 Data Bits, No parity and ONE STOP BIT (**RTU 9600-8N1**). All integers are signed unless stated. Modbus RTU requires 3.5 Character (>3.7 ms) spacing between packets. Normally the 4022 will respond within 20 ms of receiving the request from the Modbus master.



1.2 Modbus Registers

Table 1: Modbus Registers

Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
0x01 Coil Status	00100	00101	00101	Sensor 1 Alarm 1: Single Bit If Bit Value is 0 = Alarm is Off If Bit Value is 1 = Alarm is On
	00101	00102	00102	Sensor 2 Alarm1: Single Bit If Bit Value is 0 = Alarm is Off If Bit Value is 1 = Alarm is On
	00200	00201	00201	Sensor 1 Alarm 2: Single Bit If Bit Value is 0 = Alarm is Off If Bit Value is 1 = Alarm is On
	00201	00202	00202	Sensor 2 Alarm 2: Single Bit If Bit Value is 0 = Alarm is Off If Bit Value is 1 = Alarm is On
	00300	00301	00301	Sensor 1 Alarm 3: Single Bit If Bit Value is 0 = Alarm is Off If Bit Value is 1 = Alarm is On



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	00301	00302	00302	<p>Sensor 2 Alarm 3: Single Bit</p> <p>If Bit Value is 0 = Alarm is Off</p> <p>If Bit Value is 1 = Alarm is On</p>
	00400	00401	00401	<p>System Fault: Single Bit</p> <p>If Bit Value is 0 = System not in Fault</p> <p>If Bit Value is 1 = System in Fault</p>
0x03 (Holding Registers)	00100	00101	40101	<p>Sensor 1 Gas Type: 16 Bit Integer</p> <p>(See)</p>
	00101	00102	40102	<p>Sensor 2 Gas Type: 16 Bit Integer</p> <p>(See)</p>
	00200	00201	40201	<p>Sensor 1 Units of Concentration: 16 Bit Integer</p> <p>Response:</p> <ul style="list-style-type: none"> 0 = PPM 1 = % Vol. 2 = % LEL 3 = PPB



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	00201	00202	40202	Sensor 2 Units of Concentration: 16 Bit Integer Response: 0 = PPM 1 = % Vol. 2 = % LEL 3 = PPB
	00300	00301	40301	Sensor 1 Enabled: 16 Bit Integer Response: 0 = OFF 1 = ON
	00301	00302	40302	Sensor 2 Enabled: 16 Bit Integer Response: 0 = OFF 1 = ON
	00400	00401	40401	System Equipment ID: 16 Bit Integer Response: 4020
	00500	00501	40501	Sensor 1 Range: 16 Bit Integer Response: 5000 ≥ 50000 Range: = $Response \times 10^{Sensor\ 1\ Scale}$
	00501	00502	40502	Sensor 2 Range: 16 Bit Integer Response: 5000 ≥ 50000 Range: = $Response \times 10^{Sensor\ 2\ Scale}$



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	00600	00601	40601	Sensor 1 Scale: 16 Bit Integer Response: $- 4 \geq 1$
	00601	00602	40602	Sensor 2 Scale: 16 Bit Integer Response: $- 4 \geq 1$
	00700	00701	40701	Sensor 1 Alarm 1 Threshold: 16 Bit Integer Response: $5000 \geq 50000$ Threshold: $= Response \times 10^{Sensor\ 1\ Scale}$
	00701	00702	40702	Sensor 2 Alarm 1 Threshold: 16 Bit Integer Response: $0 \geq 50000$ Threshold: $= Response \times 10^{Sensor\ 2\ Scale}$
	00800	00801	40801	Sensor 1 Alarm 2 Threshold: 16 Bit Integer Response: $0 \geq 50000$ Threshold: $= Response \times 10^{Sensor\ 1\ Scale}$
	00801	00802	40802	Sensor 2 Alarm 2 Threshold: 16 Bit Integer Response: $0 \geq 50000$ Threshold: $= Response \times 10^{Sensor\ 2\ Scale}$



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	00900	00901	40901	<p>Sensor 1 Alarm 3 Threshold: 16 Bit Integer</p> <p>Response: $0 \geq 50000$</p> <p>Threshold: $= Response \times 10^{Sensor\ 1\ Scale}$</p>
	00901	00902	40902	<p>Sensor 2 Alarm 3 Threshold: 16 Bit Integer</p> <p>Response: $0 \geq 50000$</p> <p>Threshold: $= Response \times 10^{Sensor\ 2\ Scale}$</p>
	01000	01001	41001	<p>Sensor 1 Hysteresis: 16 Bit Integer</p> <p>Response: $25 \geq 10000$</p> <p>Hysteresis: $= Response \times 10^{Sensor\ 1\ Scale}$</p>
	01001	01002	41002	<p>Sensor 2 Hysteresis: 16 Bit Integer</p> <p>Response: $25 \geq 10000$</p> <p>Hysteresis: $= Response \times 10^{Sensor\ 2\ Scale}$</p>
	01100	01101	41101	<p>Sensor 1 Alarm Threshold Direction (Sign): 16 Bit Integer</p> <p>Response: 0 = Rising</p> <p>1 = Falling</p> <p>2 = Range (AL1 Rising, AL2 Falling & AL3 unused)</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	01101	01102	41102	<p>Sensor 2 Alarm Threshold Direction (Sign): 16 Bit Integer</p> <p>Response: 0 = Rising 1 = Falling 2 = Range (AL1 Rising, AL2 Falling & AL3 unused)</p>
	01200	01201	41201	<p>Sensor 1 Latching Alarms: 16 Bit Integer</p> <p>Response: 0 = Non Latching Alarms 1 = Latching Alarms</p>
	01201	01202	41202	<p>Sensor 2 Latching Alarms: 16 Bit Integer</p> <p>Response: 0 = Non Latching Alarms 1 = Latching Alarms</p>
	01300	01301	41301	<p>Sensor 1 Alarm Validation Delay: 16 Bit Integer</p> <p>Response: 0 ≥ 999 seconds</p>
	01301	01302	41302	<p>Sensor 2 Alarm Validation Delay: 16 Bit Integer</p> <p>Response: 0 ≥ 999 seconds</p>
	01400	01401	41401	<p>Sensor 1 Alarm Run On Time: 16 Bit Integer</p> <p>Response: 0 ≥ 3600 seconds</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	01401	01402	41402	<p>Sensor 2 Alarm Run On Time: 16 Bit Integer</p> <p>Response: $0 \geq 3600$ seconds</p>
	01500	01501	41501	<p>Sensor 1 Value/Status: 16 Bit Integer</p> <p>Response: [0 , 1]</p> <p>0 = Always show sensor value on screen,</p> <p>1 = Show "OK" when sensor value is within 80 % of the first alarm level</p>
	01501	01502	41502	<p>Sensor 2 Value/Status: 16 Bit Integer</p> <p>Response: [0 , 1]</p> <p>0 = Always show sensor value on screen,</p> <p>1 = Show "OK" when sensor value is within 80 % of the first alarm level</p>
	01600 - 01615	01601 - 01616	41601 - 41616	<p>Sensor 1 Location Name: String 16x Char long</p>
	01700 - 01715	01701 - 01716	41701 - 41716	<p>Sensor 2 Location Name: String 16x Char long</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	02000	02001	42001	<p>mA Output 1 Current/Voltage (Range): 16 Bit Integer</p> <p>Response: [0 , 1]</p> <p>0 = 4-20 mA Output, 1 = 0-20 mA Output.</p>
	02001	02002	42002	<p>mA Output 2 Current/Voltage (Range): 16 Bit Integer</p> <p>Response: [0 , 1]</p> <p>0 = 4-20 mA Output, 1 = 0-20 mA Output.</p>
	02002	02003	42003	<p>mA Output 3 Current/Voltage (Range): 16 Bit Integer</p> <p>Response: [0 , 1]</p> <p>0 = 4-20 mA Output, 1 = 0-20 mA Output.</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	02100	02101	42101	<p>mA Output 1 Mode: 16 Bit Integer</p> <p>Response: [0 – 8]</p> <p>0 = Off,</p> <p>1 = Sensor 1 Mirror (O/P = I/P),</p> <p>2 = Maximum of Sensor 1 & 2,</p> <p>3 = Minimum of Sensor 1 & 2,</p> <p>4 = Average of Sensor 1 & 2,</p> <p>5 = Scaled Sensor 1,</p> <p>6 = Scaled Sensor 2,</p> <p>7 = Scaled Maximum of Sensor 1 & 2,</p> <p>Scaled Minimum of Sensor 1 & 2.</p>
	02101	02102	42102	<p>mA Output 2 Mode: 16 Bit Integer</p> <p>Response: [0 – 8]</p> <p>0 = Off,</p> <p>1 = Sensor 1 Mirror (O/P = I/P),</p> <p>2 = Maximum of Sensor 1 & 2,</p> <p>3 = Minimum of Sensor 1 & 2,</p> <p>4 = Average of Sensor 1 & 2,</p> <p>5 = Scaled Sensor 1,</p> <p>6 = Scaled Sensor 2,</p> <p>7 = Scaled Maximum of Sensor 1 & 2,</p> <p>Scaled Minimum of Sensor 1 & 2.</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	02102	02103	42103	<p>mA Output 3 Mode: 16 Bit Integer</p> <p>Response: [0 – 8]</p> <p>0 = Off, 1 = Sensor 1 Mirror (O/P = I/P), 2 = Maximum of Sensor 1 & 2, 3 = Minimum of Sensor 1 & 2, 4 = Average of Sensor 1 & 2, 5 = Scaled Sensor 1, 6 = Scaled Sensor 2, 7 = Scaled Maximum of Sensor 1 & 2, Scaled Minimum of Sensor 1 & 2.</p>
	02200	02201	42201	<p>mA Output 1 Low Point Scaling: 16 Bit Integer</p> <p>Response: $0 \geq 50000$</p> <p>Point: $= Response \times 10^{Sensor\ 1\ Scale}$</p>
	02201	02202	42202	<p>mA Output 2 Low Point Scaling: 16 Bit Integer</p> <p>Response: $0 \geq 50000$</p> <p>Point: $= Response \times 10^{Sensor\ 2\ Scale}$</p>
	02202	02203	42203	<p>mA Output 3 Low Point Scaling: 16 Bit Integer</p> <p>Response: $0 \geq 50000$</p> <p>Point: $= Response \times 10^{Sensor\ 3\ Scale}$</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
	02300	02301	42301	<p>mA Output 1 High Point Scaling: 16 Bit Integer</p> <p>Response: 0 ≥ 50000</p> <p>Point: = $Response \times 10^{Sensor\ 1\ Scale}$</p>
	02301	02302	42302	<p>mA Output 2 Low Point Scaling: 16 Bit Integer</p> <p>Response: 0 ≥ 50000</p> <p>Point: = $Response \times 10^{Sensor\ 2\ Scale}$</p>
	02302	02303	42303	<p>mA Output 3 Low Point Scaling: 16 Bit Integer</p> <p>Response: 0 ≥ 50000</p> <p>Point: = $Response \times 10^{Sensor\ 3\ Scale}$</p>
	02400	02401	42401	<p>mA Output 1 Update Period: 16 Bit Integer</p> <p>Response: 0 ≥ 999 seconds</p>
	02401	02402	42402	<p>mA Output 2 Update Period: 16 Bit Integer</p> <p>Response: 0 ≥ 999 seconds</p>
	02402	02403	42403	<p>mA Output 3 Update Period: 16 Bit Integer</p> <p>Response: 0 ≥ 999 seconds</p>



Modbus Function Code	Physical Address (dec)	Offset (dec)	Legacy Address (dec)	Details
0x04 (Input Registers)	00000	00001	30001	Sensor 1 Concentration: 16 Bit Integer If Gas Range Is % LEL or % Vol. The Reading Value Is x 10
	00001	00002	30002	Sensor 2 Concentration: 16 Bit Integer If Gas Range Is % LEL or % Vol. The Reading Value Is x 10

1.4 Gas Type

16 Bit Integer	Gas Type	16 Bit Integer	Gas Type
0	CO	10	NH3
1	O2	11	NO2
2	CO2	12	Gas
3	FLM	13	R22
4	H2	14	R123



5	CH4	15	R134a
6	LNG	16	R407c
7	Prop	17	R410a
8	LPG	18	Refrg
9	H2S	19	" " (<i>Blank</i>)

Electrical Requirements:

Termination Resistors are required at both ends of the Bus if the line is longer than 30 m or if it is being used in a noisy environment. These should match the impedance of the cable used. For RS-485 Shielded Twisted Pair, this is typically 100 - 120Ω line impedance (Z_0). Ring or Star Topographies are NOT recommended for RS 485 Communications. If there is transmission trouble try to enable the bias resistors at your RS-485 master.

